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**(54) FOOD PROCESSING APPARATUS INCLUDING MAGNETIC DRIVE**

**KÜCHENGERÄT MIT MAGNETISCHEM ANTRIEB**

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**DE-B- 1 131 372 GB-A- 622 115**  
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## D scription

### Background of the Inventi n

[0001] This invention relates to a magnetic drive to transmit rotational motion from a motive source into an enclosed space without a direct mechanical connection. More specifically, it relates to blenders, mixers, and like machines, and particularly to devices having a stirrer, impeller, blade, or other tool mounted within a removable cup or container, and rotated by means of a motor located in the stationary base of the machine.

[0002] Conventional home blenders and mixers incorporate a mechanically-driven impeller rotatably mounted within a removable blender cup. The base of the cup incorporates a generally circular connection plate with a pattern of projections and/or depressions formed on its lower face that is removably mateable, using a vertical, drop-in movement, with a corresponding pattern formed on a like plate attached to the shaft of a motor housed in a base of the machine. This mechanical coupling between the blender cup and the blender motor requires a rotary seal at the base of the cup between the impeller and connecting plate. This seal is subject to considerable wear and tear over time, as is the mechanical coupling. Because seal failure can result in liquid leaking out of the cup, the seal and bearings in the base of the cup are built to ensure sealing at the expense of friction. The friction produces wear, heat, and loss of power. Moreover, the conventional blender produces much unwanted noise, and the mechanical interlocking coupling between the plates can make it awkward or difficult to remove the cup from, and return the cup to, the base.

[0003] Many drink mixers have the drive motor mounted in the base directly under the cup. If overall height is a concern, however, the motor may be positioned off to the side and coupled to the driving shaft by a belt or gear arrangement.

[0004] Known home and commercial blenders use conventional a.c. motors. While a.c. motors can be constructed and controlled to provide speed variation, as well as the requisite output torque, a typical such motor is generally bulky, heavy, and not well-suited to electronic speed control, let alone electronic braking.

[0005] While d.c. brushless motors are also known *per se*, they have not been used for blenders or blender/shavers. These motors use a comparatively heavy rotor formed of a sector-like array of permanent magnets. Blending of a mass of shaved or cubed ice and liquid, particularly on start up or during a "freeze up" of a frozen drink, requires a comparatively high torque. D.C. brushless motors are characterized by a low output torque as compared to conventional a.c. motors. They therefore have found use as a motive power source mainly in applications such as fans where a low output torque is acceptable.

[0006] A commercially viable blender/shaver for the

production of frozen drinks must satisfy a variety of special and important design criteria. It should be compact, both in its footprint and overall height, so as to utilize limited space at a bar efficiently. It ideally has a comparatively low weight. The straight-forward approach of placing a conventional electric motor directly under the blender cup increases the overall height of the machine, and therefore is not typically used. There must also be speed control, typically provided through gearing and electronics, to accommodate different power and speed requirements in different phases of operation. Rapid controlled braking is also important to limit the overall time required to blend, to avoid splashing of the blended material after blending is complete, and for safety. Control of vibration, prevention of overheating, or minimization of wear, ease of maintenance, and durability are also important.

[0007] It has also known that an impeller within a blender cup may be driven magnetically or electromagnetically rather than mechanically. One type of magnetic drive couples a rotating permanent magnet outside a blender cup or the like, to another permanent magnet rotatably mounted in the blender cup. U.S. Patent Nos. 2,459,224 to Hendricks; 2,655,011 to Ihle et al.; and 5,478,149 to Qulgg are exemplary of this approach. Hendricks discloses a magnetically operated stirrer for mixing liquids, in which the stirrer has a magnet mounted at its lower end and within the container for the liquid. Qulgg discloses a motor that drives a set of magnets, via gear box and shaft, to couple to another set of magnets mounted on an agitator.

[0008] GB Patent No. 622 115A describes a magnetic drive for a mixing element rotatably mounted on a shaft in a mixing receptacle. The mixing bowl includes a first magnet member also rotatably mounted on the shaft. The magnetic drive includes an external power source and a second magnet member. The external power source drives the second magnet member, and the second magnet member magnetically drives the first magnet member. This results in rotation of the shaft and the mixing element.

[0009] U.S. Patent No. 3,140,079 Baermann uses a large rotating plate to carry a series of circumferentially spaced magnets that pass under one portion of a much smaller, rotatable conductive disc.

[0010] U.S. Patent Nos. 1,242,493 to Stringham and 1,420,773 to Stainbrook disclose electrical drink mixers in which a stator of an a.c. motor surrounds and interacts with a rotor in a blender cup, or in its base. In Stringham, a squirrel cage rotor lies in the plane of the stator windings. In Stainbrook an a.c. rotor is mounted in the base of the blender cup and stator coils are located below the cup. Such split a.c. motor arrangements are limited by the torque, speed control, eddy current loss, and emf interference problems of a.c. motors, as accentuated by the physical separation of the stator windings and the rotor. They do not provide good speed control. They do not utilize a d.c. magnetic field coupling. And the inclu-

sion of the rotor of the motor within the container or cup adds unwanted weight to the cup assembly and makes the cup difficult to handle due to gyroscopic effects if it is picked up while the rotor is still spinning.

[0011] If the rotor of a brushless d.c. motor were to be located in the base of a blender cup, the cup would not only become heavy and exhibit a severe gyroscopic effect, but it would also "stick" to metal sinks and countertops, and would attract loose metallic implements such as silverware, barware, or coins.

### Summary of the Invention

[0012] It is therefore a principal object of this invention to provide a drive system that provides reliable, speed-controlled rotary power transmission to a rotatable driven element that is sealed from the source of motive power.

[0013] Another aspect is to provide a drive that is automatically clutched to disconnect the drive when the load exceeds a preset value or the driven member is moved from its operating position.

[0014] A further object is to provide a magnetic drive offering these advantages, in which the driver element is located in a removable blender cup and the blender cup is easy to insert and remove from the blender and is easy to handle when removed from the blender, e.g., it exhibits no significant gyroscopic effect or magnetic attraction.

[0015] Yet another object is to provide a low wear, low maintenance, nonmechanical coupling between motor and drive element, and in particular, one which avoids the high maintenance costs associated with present belt drives and mechanical clutches and brakes.

[0016] A still further object is to provide a magnetic drive for a blender or the like with the foregoing advantages which is compact, low in weight, and very easy to use and clean.

[0017] Another object is to provide a drive whose operating characteristics can be programmed and which can be braked rapidly and reliably.

[0018] In its preferred application as a drive for a blender or other food processing apparatus, the present invention employs an electric motor to rotate a ring magnet, preferably an assembly of two ring magnets with axial poles, that is closely spaced from a disc-shaped drive plate formed of a conductive, magnetizable material. The magnet assembly and drive plate each have matching, circumferentially-arrayed poles. The magnet assembly preferably has a set of an even number of generally pie-shaped, permanent magnet poles or segments of alternating polarity. The drive plate is preferably a thin sheet of a ferrous material such as cold-rolled steel with open-ended radial slots that define the poles and control eddy currents. The magnet assembly produces a sufficiently strong field (flux lines) that despite the spacing, which typically includes high reluctance air gaps, nevertheless induces oppositely polarizing mag-

netization of the disc poles. This induced magnetization couples the magnet assembly to the plate in order to drive it. In a blender, the drive plate is rotatably mounted in the base of the blender cup and supports a shaft that in turn mounts an impeller. The magnet assembly and the motor are separately housed from the drive plate.

[0019] The electric motor is preferably a brushless d.c. motor with stator windings that produce a rotating electromagnetic field that interacts with, and produce a torque on, a rotor that includes a magnet assembly like the one magnetically coupled to the disc. The rotor magnet ring is preferably secured to the drive magnet ring by bonding these magnet rings to opposite faces of a circular cold-rolled steel disc. The rotor, drive magnet ring and drive plate are co-axially aligned when the plate and its associated apparatus, such as a blending cup, are in an operating position. The motor and drive housing preferably has a flat upper wall that extends continuously through the magnet-to-plate gap, as does a flat bottom wall on the blender cup. For a magnet assembly with a field strength on its surface of 1400 gauss, the close spacing for a blender application is preferably about 0.25 inch. Use of a comparatively flat d.c. brushless motor mounted under the driven member gives the motor part of the drive a compact configuration, preferably with a height-to-width ratio of as little as about 1:3.

[0020] Viewed broadly as a method, the invention includes the steps of rotating a rotor magnet with multiple circumferentially-spaced, poles by interacting the poles with a rotating electromagnetic field. The rotor is in turn coupled to a second drive magnet with a like number of circumferentially-arrayed poles mechanically coupled to rotate in unison with the rotor. The method further includes the steps of directing the magnetic field of the drive magnet axially away from the rotor to induce oppositely polarized magnetic poles in a conductive drive plate that is rotatably mounted, and closely-spacing the drive magnet from the plate so that the induced poles in the plate follow the poles in the rotating magnet assembly despite the spacing and despite a load that resists rotation. The directing of the magnetic field includes bonding the magnets in a sandwich fashion to opposite faces of a thin steel disc and polarizing the ring magnets axially.

[0021] In accordance with another aspect of the present invention, the drive of the present invention can include a gear assembly having one or more gears for transmitting torque from the drive plate to a driven member such as, for example, an output shaft. The gear assembly can include one or more gears sized and arranged to reduce, or to increase, the torque transmitted from the drive plate to the driven member. In a preferred application, the drive and gear assembly are employed to rotate the blade of an ice shaver. The ice shaver can be a stand alone unit or can be incorporated with a blender, such as the blender of the present invention, to form an automatic blender/ice shaver machine for manufacturing frozen drinks.

[0022] These and other features and objects of the invention will be more fully understood from the following detailed description that should be read in light of the accompanying drawings.

### **Brief Description of the Drawings**

[0023]

Fig. 1 is a view in perspective of a blender/shaver machine constructed according to the present invention;

Fig. 2 is a view in vertical section of the blender/shaver machine of Fig. 1;

Fig. 3 is an exploded perspective view of the blender cup shown in Figs. 1 and 2;

Fig. 4 is a detailed view in vertical section of the magnetic drive of the present invention as shown in Fig. 2 used to power an impeller mounted in the base of a blender cup;

Fig. 5 is an exploded perspective view of the base of the blender/shaver shown in Figs. 1 and 2 showing the mounting of the motor assembly for the magnetic drive according to the present invention;

Fig. 6 is a view in perspective of the double magnet assembly shown in Fig. 4;

Fig. 7 is a view in vertical section of an alternative embodiment of the blender cup of the present invention;

Fig. 8 is a view in vertical section of the magnetic drive and gear assembly for the ice shaver portion of the blender/shaver of the present invention; and

Fig. 9 is a view in vertical cross-section along line F-F of Fig. 8 of the magnetic drive and gear assembly of Fig. 8.

### **Detail Description of the Preferred Embodiments**

[0024] Figs. 1 and 2 show a principal application of the present invention, namely, in a blender/shaver machine 10 adapted to the automatic manufacture of frozen drinks in bars and restaurants. A supply of ice in a hopper 12 is fed by a rotating set of blades 14 to a blade 16. The shaved ice falls through a chute 18 including a lid 20 into a blender cup 22 to which liquid ingredients such as a flavor concentrate and/or spirit have been added. Rotation of an impeller (or blade set) 24 at the bottom of the cup for a preset period of time produces a high quality frozen drink - one that peaks when poured and has a generally uniform, non-marbled, non-

watery consistency. While the invention will be described below principally with reference to use in the blender/shaver 20, it will be understood that the invention can be used in a wide variety of applications where it is desired to transmit power from a rotary output of a motive source (e.g., a motor) to a driven member under a load, particularly a rotating driven member held in a container that is sealed from and removable from the motive source. The invention can be used, for example, in a variety of food processing equipment such as home blenders, food mixers, food processors and juicers.

[0025] A magnetic drive 26 for the impeller 24 is the focus of the present invention. With reference to Figs. 3-5, the drive 26 includes a generally circular drive plate 34 rotatably mounted in the base 22a of the blender cup 22 and a brushless d.c. motor 28 including stator coils 30 and a rotor 32. The rotor in turn includes a double magnet assembly 35 preferably formed of a rotor ring magnet 36, a drive ring magnet 38 and a disc 40 of a magnetizable material, preferably cold-rolled steel, bonded between the magnets 36 and 38.

[0026] The ring magnets 36 and 38 each have multiple circumferentially-arrayed, axially-directed poles 42, eight as shown in Fig. 6. Laterally adjacent segments have the opposite polarity. While eight poles are preferred, any even number can be used. Preferably each pole 42 is developed by a generally pie-shaped permanent magnet region 44 formed in a continuous ring of a strongly magnetic material such as the ceramic magnets sold by Hitachi Corporation. The magnet regions 44 in each magnet 36 and 38 can also be separate pieces bonded or otherwise mechanically secured to one another to form a ring assembly with flat faces and a generally cylindrical outer wall. A plastic hub 43 with radially directed support walls 43a fills the center of the magnets 36, 38 to facilitate mounting the assemblies on a central shaft. A north pole magnet region 44 is adjacent a south pole magnet region 44. Assemblies 36 and 38 are then affixed to the disc 40, preferably with each permanent magnet region 44 in one assembly overlying a like magnet region in the other assembly, but having the opposite polarity to avoid the repulsive magnetic force between the magnets 36 and 38. A plastic overlayer 48 helps to secure the sandwich assembly. This magnet assembly configuration with axially oriented magnetic pole regions 44, and the low reluctance return path presented by the steel disc 40 for all of the magnet regions 44, directs the magnetic field (lines of flux) of the rotor magnet 36 axially (downwardly as shown) toward the stator coils 30 and the magnetic field of the drive magnet 38 axially (upwardly as shown) toward the plate 34 in the cup base 22a. The strength and this axial directing of the field of the drive magnet 38 induce magnetic fields of opposite polarity in a corresponding poles 24a formed in the drive plate 34 despite the presence of a spacing 46, albeit a close spacing, between the generally flat upper surface 38a of the magnet assembly and the generally flat lower surface 34b of the

plate 34.

[0027] In the preferred form illustrated and shown for the blender/shaver (used to blend up to 80 fluid ounces of a frozen drink), the permanent magnet 36 develops a magnet field strength of about 1400 gauss at its surface, and the spacing 46 is about 0.25 inch measured axially. This spacing includes, as shown in Fig. 4, not only four layers 48, 50a, 52, 22b of what is typically a plastic material, but also air gaps 54 and 56. Layers 48 and 52 are a thin plastic over-molding for the magnet assembly 35 and the drive plate 34, respectively. The layer 50a is the flat upper wall portion of a base 50 of the blender/shaver 10. Layer 22b is the flat lower wall of the cup base 22a.

[0028] The air gap 54 is a slight clearance between the rotor over-molding 48 and the wall 50a. The gap 56 is a slight clearance between the wall 22b and the drive plate over-molding 52. As will be readily appreciated by those skilled in the art, this spacing is a significant source of reluctance in the magnet circuit between the ring drive magnet 38 and the plate 34. Permanent magnet rotors of known d.c. brushless motors, e.g., the 5 inch disc-diameter motor sold by Integrated Motion Controls, LLC of Torrington, Connecticut under its Model No. 50, while roughly comparable in size, construction and field strength to the magnet 38, cannot couple to the plate 34 across the spacing 46 with sufficient strength to drive the disc operating a blender/shaver.

[0029] With particular reference to Figs. 4 and 5, the motor 28 is mounted in the base 50 by screws 60 that pass through a steel motor cover 62 and a rear stator support 64 into threaded sockets 66 formed in a motor mount wall 50b of the base. The rear stator support 64 has a central opening that holds a bearing assembly 68 that journals a motor shaft 70. Screws (not shown) passing through openings 54a in the rear stator support thread into and secure a front stator support 72 to sandwich a ring 74 of back steel in the assembly adjacent the coils 30. The front stator support 72 has a periphery 72a that is sloped and slotted to carry the stator windings 30 as in the aforementioned Model 50 motor. (The portions of the windings in the slots are not shown for clarity.) The windings are three phase, being energized by a conventional brushless d.c. motor drive circuit to produce a rotating electromagnetic field. The base and stator supports are preferably formed of a moldable, high-strength plastic, and with a wall thickness, that rigidly supports the motor 28.

[0030] The double magnet assembly 35 with the shaft 70 secured at its center slides axially into the bearing 68 (Fig. 4). The assembly 35 rotates in the bearing 68 with a clearance on all sides of the assembly 35. As noted above, the multi-pole, d.c. magnetic field produced principally by the lower (as shown) rotor magnet 36 is directed principally downwardly to interact with the rotating electromagnetic field produced by the stator coils 30 when they are energized. Rotation of this electromagnetic field interacting with the rotor magnet assembly

produces a torque that rotates the rotor at a like rotational speed. The disc 40 bonded between the magnets 36 and 38 transmits this torque to the plate drive magnet 38. As a safety precaution against combustion should the coils 30 overheat, a ring-like shroud 76 has a lower flange 76a that extends substantially across the air gap between the outer edge of the assembly 35 and the generally cylindrical inner side wall of the rear stator support 64 (with a slight clearance to avoid frictional contact with the magnet assembly 35). The shroud fills this gap sufficiently to impede an air flow that would otherwise feed oxygen to a fire.

[0031] The magnet assembly 35 in a five-inch diameter weighs approximately three pounds. With typical operating speeds varying from 4,000 to 10,000 rpm, it can exert significant forces on the mounting structures, particularly rapidly varying forces that produce vibrations. The mounting structure is made sufficiently rigid, through choice and dimensions of materials as well as the overall design, e.g., the use of wall reinforcements such as exterior ribs, to resist the forces and moments produced in normal operation, and thereby to control vibrations that would otherwise loosen, wear and the extreme, eventually destroy the motor.

[0032] Position of the rotor is sensed by three conventional Hall effect sensors mounted in a known manner in the motor housing, or the base 50. Position signals provide input to a known electronic control and drive circuit that energizes the three phase stator windings 30 to produce (i) a start-up torque, (ii) a ramp up of the rotor speed of rotation to a selected operating speed, (iii) a maintained rotation at that selected speed under load, and then (iv) a rapid and reliable braking. Operating of the motor is thus electronically controlled and programmable. Braking is electronic - - with the braking currents induced in the windings 30 being dissipated in large resistors or FET's mounted on heat sinks.

[0033] With reference to Figs. 2-4, and especially Figs. 3 and 4, the conductive drive plate 34 is non-rotatably secured to the lower end of a shaft 78 that is journaled in a stacked pair of needle bearing assemblies 80. A surrounding brass collar 82 press fit into a central, cylindrical-walled opening 22c in the plastic base 22a holds the bearing assemblies 80. At the bottom of the cup, the collar 82 has an enlarged diameter counter bore that receives and secures a rotary seal 84 formed of a suitably elastomeric material such as a wear-resistant rubber. The seal has three inwardly facing, mutually-spaced lips 84a whose inner edges each engage, and provide a low-friction running or sliding seal around the shaft 78. The seal 84 retains liquid in the cup 22 despite the presence of a rotating shaft penetrating the bottom wall of the cup. The lower-most lip 84a engages the shaft 78 in a circumferential groove that locates and stabilizes the seal. A deep circular groove 84b in the lower face of the seal allows the lips to flex resiliently, yet lightly, against the shaft. Above the seal, an acorn nut 86 threaded on the upper end of the shaft 78

secures the blades 24 sandwiched between three washers 88a, 88b, and 88c.

[0034] The drive plate 34 is part of a drive plate assembly that includes a set of vertical, radially-arrayed, reinforcing ribs 90 angularly centered over each pole 34a (Fig. 3). The ribs 90 and a central boss 91 that surrounds the shaft 78 are preferably molded continuously with the bottom layer 52. The plate 34 is preferably formed of a thin sheet of a ferrous material such as cold-rolled steel, e.g., 0.058 inch thick, with a set of open-ended radial slots 92 that produce the poles 34a. The slots 92 also control eddy currents induced in the plate by the rotating field of the drive magnet assembly 38. Because the plate 34 is thin and slotted, it can deform when it is subjected to the significant attractive magnetic force of the plate drive magnet assembly 38, e.g., typically about five pounds, and be placed in frictional contact with the cup base 22b. The ribs 90 and the overmolding generally help the plate to retain its flat configuration.

[0035] As shown, the attractive magnetic force acting on the drive plate 34 is preferably carried at a single, central pivot point formed by a hemispherical ball-bearing projecting from the bottom surface of the drive assembly and a stainless steel plate 96 mounted flush with the upper surface of the cup base wall 22b. This arrangement resists the magnet forces pulling down on the plate 34 while at the same time facilitating a low-friction, low-wear rotation of the shaft 78.

[0036] With reference to Fig. 7, in an alternative embodiment of the blender cup 122, the shaft 178 is rotatably supported by two axially spaced needle bearings 200a and 200b. A cylindrical spacer 202 is interposed between the needle bearings 200a and 200b and surrounds the shaft 178. The drive plate 134 is attached to the shaft 178 through a screw 206 having external threads for mating with complementary internal threads formed in the shaft 178. A flange 204 can be provided at the end of the shaft 178 and the drive plate 134 is sandwiched between the flange 204 and a washer 208 adjacent the head of screw 206. This particular arrangement allows the shaft 178 to be rotatably supported by the needle bearings 200a and 200b and the screw 206 without the need for the hemispherical ball-bearing projecting from the bottom surface of the drive assembly and the stainless steel plate 96 mounted within the cup base wall. It should be understood that the component parts of the embodiment of Fig. 7 are similar to those previously described herein, and accordingly the same reference numerals are used to designate similar parts although the numerals are incrementally increased by 100 to differentiate the embodiments described herein.

[0037] It has been found that the coupling, or "traction", between the magnet 38 and the drive plate 34 increases not only as a function of the strength of the magnetic field acting on the poles 34a and the closeness of the magnet-to-disc spacing, but also as a function of the thinness of the plate 34 and the width of the slots 92. In

general, the thinner the plate and the wider the slots, the more traction is produced for a given magnet and spacing. The presently preferred slot width for an eight-pole, 4.425 inches diameter plate is about 0.245 inch.

[0038] The desired level of traction depends on each application. It is selected to reliably couple the drive plate to the drive magnet when (i) the impellers 24 are started under the load of the shaved ice and liquid ingredients of a frozen drink in the blender cup, (ii) during a ramp up of the operating speed to a selected operating speed, typically thousands of rpm, and then (iii) as the impeller, and the slushy mass in the cup and interacting with the impeller, is brought to a stop. However, the traction is also selected to disconnect, and thereby automatically clutch, the drive 26 when the cup 22 is removed from its operating position on the base wall 50a under the ice chute 18, or when the load exceeds a preset maximum value. This latter situation can arise, for example, when the frozen drink "freezes up" in the cup, that is, becomes partially or totally a solid frozen mass, or when an object inadvertently falls into the blender as it is operating, e.g., a spoon, jewelry, or bottle cap. By de-coupling, the magnetic drive 26 automatically and immediately cuts off power to the impellers to avoid or minimize injury to person(s) near the blender and to the machine itself. This feature also avoids the cost of providing and maintaining a mechanical clutch.

[0039] While brushless d.c. motors are known as having comparatively low torque outputs, the present invention has been found to overcome this deficiency. However, to optimize the performance of the motor 28, the stator coils 30 are preferably wound to optimize the torque output at a preselected operating speed, e.g., near 8,000 rpm.

[0040] It is significant to note that the drive plate assembly, mainly a thin metal disc and plastic molding over it, are light and non-magnetic. There is little detectable gyroscopic effect when the cup is removed from the blender/shaver after use. There is a low rotational momentum due to the impellers and drive plate assembly. Because the cup is light-weight and nonmagnetic, it is easy to handle.

[0041] It is also quite significant that the magnetic drive 26 of the present invention allows the cup 22 to be placed in an operating position on the blender/shaver 10 with a simple, lateral sliding movement over the smooth, flat cup base 22b over the smooth, flat base portion 50a. There is no need to drop the cup vertically onto a mechanically interlocking drive coupling, and then vertically lift the cup off this coupling. The lateral sliding insertion and removal movements are not only more convenient, but they also reduce the vertical clearance required above the cup. This slide-in arrangement also facilitates cleaning the blender base - one need only wipe a smooth surface. Spilled liquid and slush can flow or be pushed over the surface to a drain 94 formed in the base at the rear of the wall 50a. In the event of a safety hazard, blender overload, or any un-



sual situation requiring a rapid removal of the cup, it is simply and rapidly withdrawn from the machine with a sliding motion. Further, and quite importantly, if an operator is impatient and removes the cup before the motor has fully stopped, a common problem in actual use in a bar, the process of removal itself automatically disconnects the impeller drive from the motor 28 (a misalignment and/or lifting of the cup moves the poles 34a out of a coupled relationship with the magnetic lines of force produced by the magnet assembly 38.) In conventional belt driven, mechanically-clutched blender/shavers, such a premature removal causes stress and wear on the drive train and the clutch.

[0042] A further significant advantage of this drive is that it places the motor directly under the blender, thus eliminating drive belts or chains and pulleys or sprockets, but does so while still maintaining vertical, as well as horizontal compactness, both in terms of the height of the motor itself, the vertical height of the coupling between the motor and the cup, and the vertical clearance needed to maneuver the cup onto and off the coupling.

[0043] While this invention has been described with respect to its preferred embodiment, it will be understood that various modifications and variations will occur to those skilled in the art. For example, while this invention has been described as powered by a d.c. brushless motor, it is possible to achieve some of the advantages of this invention by using an a.c. motor whose output shaft is coupled to the plate drive magnet. While a rotating magnet assembly has been described as the member coupling to the plate in the cup base, it is possible to produce a rotating electromagnetic or magnetic field using an assembly of electromagnets or other permanent magnet arrangements such as a single, one-piece permanent magnet magnetically configured, or acting in combination with ferromagnetic materials, to produce the desired array of magnetic poles. While the invention has been described with reference to a plate rotatable in the base of a blender cup, the driven element could assume a wide variety of other forms, and need not even be a liquid-holding vessel. While the magnets and plate have been described as having the same number of poles, as is well known, this is not essential to the operating of this invention. A variety of mounting and rotational support arrangements are possible for both the double magnet assembly 35 and the driven conductive plate 34. Further, while a radially slotted plate 34 has been described as forming the poles 34a and controlling eddy currents in the plate, one skilled in the art will readily see that a variety of other known arrangements for forming poles and controlling eddy currents are possible. Still further, while the magnets have been described as bonded to a metal disc, it is not necessary to use this disc.

[0044] Figs. 2, 8, and 9 illustrate a further application of the present invention, namely, in an ice shaver assembly for supplying shaved ice to the blender of the blender/shaver machine 10. The ice shaver assembly

includes a magnetic drive and gear assembly 300 that operates to rotate blades 14 to supply shaved ice to the blender cup 22 through chute 16. The magnetic drive and gear assembly 300 is coupled to an output shaft 302 that is connected at its upper end to the rotating set of blades 14. The magnetic drive and gear assembly 300 includes a magnetic drive 304 that is analogous in structure and operation to the magnetic drive 26 of the blender. The output of the magnetic drive is transmitted through a gear assembly 306 to the output shaft 302 of the shaver. The gear assembly includes three gears, namely, a motor gear 328, a compound idler gear 332, and an output gear 334.

[0045] The magnetic drive 304 for the shaver includes a generally circular drive plate 308 rotatably mounted in the motor housing 309 of the ice shaver assembly and a brushless d.c. motor 310 including stator coils 312 and rotor 314. The rotor 314 in turn includes a double magnetic assembly preferably formed of a rotor ring magnetic 316, a drive ring magnetic 318, and a disk 320 of a magnetizable material, preferably cold-rolled steel, bonded between the magnets 316 and 318.

[0046] The ring magnets 316 and 318 each have multiple circumferentially-arrayed, axially-directed poles, as in the case of the ring magnets 36 and 38 of the magnetic drive of the blender described above. The ring magnets 316 and 318, thus, have poles constructed and arranged in a manner analogous to the ring magnets 36 and 38 of the magnetic drive of the blender. A plastic hub 321 fills the center of the ring magnets 316 and 318 to facilitate mounting the magnets on a central shaft 322. The ring magnets are affixed to the disk 320, preferably with each pole in one ring magnet overlying a pole of the other ring magnet having the opposite polarity to avoid the repulsive magnetic force between the magnets 316 and 318. A plastic overlayer enclosing the magnets 316 and 318 and the disk 320 can help secure the magnet assembly.

[0047] The brushless d.c. motor 310 is mounted in the motor housing 309 beneath the rotor 314. The motor 310 is constructed and operates in a manner analogous to the motor 28 of the magnetic drive 26 of the blender described above. The stator coils 312 are three phase coils being energized by a conventional brushless d.c. motor drive circuit to produce a rotating electromagnetic field. The rotor 314 with the shaft 322 secured at its center slides axially into a bearing 324. The rotor 314 rotates in the bearing 324 with clearance on all sides of the rotor 314. The d.c. magnetic field produced principally by the lower rotor ring magnet 316 is directed principally downward to interact with the rotating electromagnetic field produced by the stator coils 30 when the coils are energized. Rotation of this electromagnetic field interacting the rotor magnetic assembly 314 produces a torque that rotates the rotor at a like rotational speed. The disk 320 bonded between the magnets 316 and 318 transmits this torque to the drive ring magnet 318.

[0048] As in the case of the rotor 32 of the magnetic

drive 26 of the blender, described above, the position of the motor 314 can be sensed by three conventional Hall effect sensors mounted in the motor housing 309. Position signals provide input to an electronic control and drive circuit that energizes the three phase stator windings 312 to produce a startup torque, a rampup of the rotor speed of rotation to a selected operating speed, a maintained rotation at that selected speed under load, and a rapid and reliable braking torque. As in the case of the motor 28 described above, operation of the motor 310 thus can be electronic and programmable. Braking is electronic — with braking currents induced in the windings 312 being dissipated in large resistors or FET's mounted on heat sinks.

[0049] The drive plate 308 can be structured in a manner analogous to the drive plate 34 of the magnetic drive 26 of the blender described above. The drive plate 308 is non-rotatably secured to the lower end of a drive shaft 326. The motor gear 328 is non-rotatably attached to a motor gear shaft 329 which in turn is attached to the upper end of the drive shaft 326. The motor gear 328 is preferably a helical gear having a plurality of helical gear teeth 350. The drive shaft 326 axially fits within the gear shaft 329 and is non-rotatably secured to the gear shaft 329 and the gear 328 to permit the drive shaft 326 and the gear 328 to rotate in unison. Thus, rotational torque from the drive plate 308 can be transmitted to the gear 328 through the drive shaft 326. The drive shaft 326 and the gear shaft 329 of the motor gear 328 are rotatably supported by a pair of journal bearings 330a and 330a.

[0050] The compound idler gear 332 is mechanically coupled to the motor gear 328 and the output gear 334 to transmit rotational torque from the motor gear 328 to the output gear 334. The idler gear 332 includes an elongated, cylindrically-shaped upper gear portion 332a having a plurality of helical gear teeth 352 and a generally disk-shaped lower gear portion 332b. The lower gear portion 332b is provided with a plurality of helical gear teeth 354 complementary in size and shape to the gear teeth 350 of the motor gear 328. The gear teeth 350 of the motor gear 328 engage the gear teeth 354 of the lower gear portion 332b to transmit rotational motion and torque from the motor gear 328 to the idler gear 332. The compound idler gear 332 is non-rotatably secured to a gear shaft 356 which is rotatably supported by a pair of journal bearings 333a and 333b.

[0051] The output gear 334 is generally cylindrical in shape and is non-rotatably attached to the output shaft 302 to rotate with the output shaft 302. In particular, the output gear 334 is axially disposed over the output shaft 302 such that the output shaft is fitted within the central opening of the output gear 334. The output gear 334 is provided with a plurality of helical gear teeth 334a complementary in size and shape to the gear teeth 352 of the upper gear portion 332a of the idler gear 332. The gear teeth 352 of the upper gear portion 332a engage the gear teeth 334a of the output gear 334 to transmit rotational motion and torque from the idler gear 332 to

the output gear 334. The output shaft 302 and the output gear 334 are rotatably supported by a pair of journal bearings 336a and 336b.

[0052] The rotor gear 328, the idler gear 332, and the output gear 334 are preferably helical gears, having helically oriented gear teeth, constructed of light weight, high strength plastic material, such as acetyl or nylon. One skilled in the art will recognize, however, that other gear types, such as spur gears, worm gears or combinations thereof, and other materials, such as metals or composites can be used in the gear assembly 306 of the present invention.

[0053] The gear ratio of the gear assembly 306 of the present invention can be adjusted to increase or to decrease the rotational speed and torque transmitted from the drive shaft 326 of the magnetic drive 304 to the output shaft 302 of the ice shaver. For example, the gear ratio of the gear assembly 306 can be adjusted to reduce the rotational speed, and thus increase the torque, transmitted from the drive shaft 326 to the output shaft 302. Conversely, the rotational speed transmitted by the gear assembly 306 can be increased, thereby reducing the torque transmitted, by adjusting the gear ratio of the gear assembly 306. The gear ratio can be adjusted by changing the number of gear teeth, the number of gears, and/or the size of gears of the gear assembly, as known in the art.

[0054] In the preferred embodiment of the ice shaver of the present invention, the desired speed of the output shaft 326 of the ice shaver is approximately 540 rpm for effective operation of the ice shaver. The magnetic drive 300 of the present invention, employing a brushless d. c. motor as is preferred, typically generates an operational speed of approximately 6000 rpm. Accordingly, the gear ratio of the gear assembly 306 is approximately 11.1:1.

[0055] One skilled in the art will readily appreciate that the magnetic drive and gear assembly of the present invention can be used in a wide variety of applications, in addition to the ice shaver described above, where it is desired to transmit power from a rotary output of a motor to a driven member under a load, including in other food processing equipment such as blenders, food mixers, food processors, and juicers.

[0056] Additionally, although the ice shaver of the present invention is described as a component of a combination blender/ice shaver machine, one skilled in the art will readily appreciate that the ice shaver can be a stand alone unit, i.e., the ice shaver can be independent of the blender.

[0057] Moreover, one skilled in the art will appreciate that the type and number of gears, the size of the gears, and the number of gear teeth of the gear assembly described herein in connection with the ice shaver of the present invention is exemplary only. These features, as well as other features of the gear assembly, can be varied to achieve the same, similar or, different gear ratios, as is desired for a specific application, without departing



from the scope of the present invention. For example, design considerations, such as weight and size limitations, can dictate the number, type, and size of gears, as well as the number of gear teeth, employed to achieve the desired gear ratio.

[0058] These and other modifications and variations which will occur to those skilled in the art having read the foregoing specification in light of the accompanying drawings are intended to fall within the scope of the appended claims.

## Claims

1. A drive (26) for rotating a driven member (24), said drive comprising:

a drive plate (34) formed of magnetizable material coupled to said driven member (24) to rotate therewith,

a motor (28) positioned proximate said drive plate (34) said motor having a stator (30) and a rotor (32), said rotor (32) including a rotor magnet (36), said stator (30) producing an electromagnetic field that interacts with said rotor magnet (36) to rotate said rotor magnet (36), and

a drive magnet (38) coupled to said rotor magnet (36) to rotate therewith, said drive magnet (38) inducing a magnetic field in a direction toward said drive plate (34) to transmit a drive torque from said motor (28) to said drive plate (34) to rotate said driven member (24).

2. The drive of Claim 1, wherein said motor (28) is an electric motor.

3. The drive of Claim 2, wherein said electric motor (28) is a brushless d.c. motor.

4. The drive of any preceding claim, wherein said drive magnet (38) and said rotor magnet (36) each include a plurality of poles (42).

5. The drive of Claim 4, wherein said drive magnet (38) and said rotor magnet (36) have a like number of poles (42).

6. The drive of Claim 5, wherein said poles (42) of said drive magnet (38) are aligned by pole polarity with said poles (42) of said rotor magnet (36).

7. The drive of any of claims 4 to 6, wherein said poles (42) of said drive magnet (38) and said poles (42) of said rotor magnet (36) are circumferentially-aligned.

8. The drive of any of claims 4 to 7, wherein said drive

plate (34) includes a plurality of radial directed open slots (92) that define a plurality of poles (34a) on said drive plate (34).

9. The drive of Claim 8, wherein said drive plate (34) and said drive magnet (38) have a like number of poles, said poles (34a) of said drive plate (34) being aligned with said poles (42) of said drive magnet (38).

10. The drive of Claim 9, wherein said drive plate (34) is formed of cold-rolled steel.

11. The drive of Claim 8, wherein said drive plate (34), said drive magnet (38), and said rotor magnet (36) each have eight poles.

12. The drive of any preceding claim, wherein said drive magnet (38) and said rotor magnet (36) are centered on a common axis of rotation.

13. The drive of Claim 12, wherein said common axis is coaxially aligned with the axis of rotation of said drive plate (34).

14. The drive of any preceding claim, further comprising a plate (40) of magnetizable material secured between said drive magnet (38) and said rotor magnet (36).

15. The drive of Claim 14, wherein said rotor magnet (36), said drive magnet (38), and said plate (40) are enclosed within a layer of a plastic material (48).

16. The drive of any preceding claim, further comprising a first housing (22a) enclosing said drive plate (34) and a second housing (50) enclosing said motor (28), said rotor magnet (36), and said drive magnet (38), and wherein said drive plate (34) is rotatably mounted in said first housing (22a) in a closely spaced (46), axially aligned relationship with said drive magnet (38).

17. The drive of Claim 16, wherein said close spacing (46) accommodates (i) an upper wall (50a) of said second housing (50), (ii) a lower wall (22b) of said first housing (22a), (iii) an air gap (56) between said lower wall (22b) and said drive plate (34), and (iv) an air gap (54) between said upper (50a) wall and said drive magnet (38).

18. The drive of Claim 16, wherein said drive magnet (38) has a field strength of about 1400 gauss at its surface and said close spacing (46), measured axially, is about 6.35mm (0.25 inch)

19. The drive of any preceding claim, wherein said motor (28) and drive magnet (38) have a maximum

height-to-width ratio of about 1:3, where height is measured along the axis of rotation of said motor (28) and said drive magnet (38).

20. The drive of any preceding claim, wherein said motor (28) includes an output shaft (70) secured to said rotor (32) and rotatable within said stator (30) in bearings (68), a rear stator support (64) that supports said bearings (68) at its center and has rigid, generally cylindrical side walls surrounding said stator (30) and said rotor (32) with a gap, and a shroud (76) that spans said gap. 5
21. The drive of any preceding claim, wherein said rotor magnet (36) and drive magnet (38) each are a single ring magnet. 10
22. The drive of any preceding claim, wherein said driven member (24) is a shaft (78) of a food processing apparatus. 15
23. The drive of Claim 22, wherein said food processing apparatus is a blender, an ice shaver, a food mixer, a food processor, or a juicer. 20
24. The drive of Claim 22, wherein said food processing apparatus includes a receptacle (22) for receiving food for processing, said receptacle having a rotatable element (24) mounted on said shaft (78). 25
25. The drive of Claim 24, further comprising a seal (84) positioned about said shaft (78) to provide a fluid seal between said receptacle (22) and said shaft (78). 30
26. The drive of Claim 24, wherein said rotatable element (24) is a blade for processing food. 35
27. The drive of any preceding claim, further comprising a gear assembly (306) including one or more gears (328, 332, 334) coupled to said drive plate (308) and to said driven member (14), said gear assembly (306) transmitting said drive torque from said drive plate (308) to said driven member (14). 40
28. The drive of Claim 27, wherein the gear assembly (306) increases the drive torque transmitted from said drive plate (308) to said driven member (14). 45
29. The drive of Claim 27, wherein the gear assembly (306) decreases the drive torque transmitted from said drive plate (308) to said driven member (14). 50
30. The drive of Claim 27, wherein said drive plate (308) is secured to a drive shaft (326) to rotate with said drive shaft (326). 55
31. The drive of Claim 30, wherein said drive magnet (318) and said rotor magnet (316) are centered on a common axis of rotation.
32. The drive of Claim 31, wherein said common axis is coaxially aligned with said drive shaft (326).
33. The drive of Claim 32, wherein said driven member (14) rotates about an axis of rotation offset from said common axis of rotation.
34. The drive of Claim 30, wherein a first gear (328) of said gear assembly (306) is secured to said drive shaft (326) to rotate therewith.
35. The drive of Claim 34, wherein a second gear (334) of said gear assembly (306) is coupled to said driven member (14) to rotate therewith, said first gear (328) and second gear (334) interacting to transmit said drive torque from said drive plate (308) to said driven member (14).
36. The drive of Claim 35 wherein said gear assembly (306) further comprises a third gear (332) interposed between said first gear (328) and said second gear (334), and said third gear (332) interacting with said first gear (328) and said second gear (334) to transmit said drive torque therebetween.
37. The drive of any preceding claim, further comprising a control and drive unit electrically coupled to said motor (28) to control operation of said motor (28), said control and drive unit selectively energizing said stator (30) to produce an operating torque or a braking torque on said rotor (32).
38. The drive of Claim 37, wherein said stator (30) includes one or more stator coils.
39. The drive of Claim 38, wherein said control and drive unit varies current through said stator coils to produce said operating torque or said braking torque.
40. The drive of Claim 37, further comprising one or more position sensors coupled to said control and drive unit to monitor the location of said rotor (32).
41. The drive of Claim 40, wherein the position sensors are Hall effect sensors.
42. A method of operating a food processing apparatus, the food processing apparatus including a food receptacle (22) having a rotating element (24) mounted on a shaft (78), a drive plate (34) formed of magnetizable material secured to said shaft (78) to rotate therewith, and a magnet assembly (36, 38) magnetically coupled to a motor (28) and said drive plate (34), the method comprising the steps of:

transmitting an operating torque at an operating speed from said motor (28) to said drive plate (34) through said magnet (36, 38) assembly to effect rotation of said shaft (78) and said rotating element (24), and  
transmitting a braking torque from said motor (28) to said drive (34) plate through said magnet assembly (36, 38) to terminate rotation of said shaft (78) and said rotating element (24).

43. The method of Claim 42, wherein said operating torque and said braking torque are transmitted from said motor (28) to said drive plate (34) without mechanical coupling of said drive plate (34) to said motor (28).

44. The method of Claim 42, wherein the step of transmitting an operating torque comprises

transmitting a start-up torque from said motor (28) to said drive plate (34),  
increasing the speed of rotation of said drive plate (34) to said operating speed, and  
maintaining said operating speed at said operating torque.

45. The method of Claim 42, wherein the motor (28) is a brushless d.c. motor having one or more stator coils (30) and wherein said operating torque and said braking torque are generated by varying current through said stator coils (30).

46. A food processing apparatus comprising:

a blender comprising

a blender cup (22) having a first blade (24) rotatably mounted on a first shaft (78),  
a first drive (34) plate formed of magnetizable material secured to said first shaft (78) to rotate therewith,  
a first motor (28) positioned proximate said first drive plate (34), said first motor (28) having a first stator (30) and a first rotor (32), said first rotor (30) including a first rotor magnet (36), said first stator (30) producing an electromagnetic field that interacts with said first rotor magnet (36) to rotate said first rotor magnet (36),  
a first drive magnet (38) coupled to said first rotor magnet (36) to rotate therewith, said first drive magnet (38) inducing a magnetic field in a direction towards said first drive plate (34) to transmit a drive torque from said first motor (28) to said first drive (34) plate thereby rotating said first shaft (78) and said first blade (24); and

an ice shaver for supplying shaved ice to said blender, said ice shaver comprising

an ice hopper (12) having a second blade (14) rotatably mounted on a second shaft (302), and said ice hopper (12) including a chute (16) connected to said blender cup (22) for supplying shaved ice to said blender cup (22),

a second drive plate (308) formed of magnetizable material,

a second motor (310) positioned proximate said second drive plate (308), said second motor (310) having a second stator (312) and a second rotor (314), said second rotor (314) including a second rotor magnet (316), said second stator (312) producing an electromagnetic field that interacts with said second rotor magnet (314) to rotate said second rotor magnet (316).

a second drive magnet (318) coupled to said second rotor magnet (316) to rotate therewith, said second drive magnet (318) inducing a magnetic field in a direction toward said second drive plate (308) to transmit torque from said second motor (310) to said second drive plate (308), and  
a gear assembly (306) including one or more gears (328, 332, 334) coupled to said second drive plate (308) and to said second shaft (302), said gear assembly (306) transmitting said drive torque from said second drive plate (308) to said second shaft (302) to effect shaving of said ice with said second blade (14).

#### Patentansprüche

1. Antrieb (26) zur Inrotationsversetzung einer angetriebenen Komponente (24), welcher Antrieb umfasst:

eine Antriebsplatte (34) aus magnetisierbarem Material, die mit der angetriebenen Komponente (24) verbunden ist, um damit zu rotieren, einen Motor (28) positioniert nahe der Antriebsplatte (34), welcher Motor über einen Stator (30) und einen Rotor (32) verfügt, welcher Rotor (32) einen Rotormagneten (36) enthält, welcher Stator (30) ein elektromagnetisches Feld erzeugt, das mit dem Rotormagneten (36) wechselwirkt, um den Rotormagneten (36) in Rotation zu versetzen, und  
einen Antriebsmagneten (38), verbunden mit dem Rotormagneten (36), um damit zu rotieren, welcher Antriebsmagnet (38) ein magnetisches Feld in Richtung auf die Antriebsplatte

- (34) zu induziert, zur Übertragung eines Antriebsdrehmomentes von dem Motor (28) zur Antriebsplatte (34), um die angetriebene Komponente (24) in Rotation zu setzen.
2. Antrieb nach Anspruch 1, worin der Motor (28) ein elektrischer Motor ist.
  3. Antrieb nach Anspruch 2, worin der elektrische Motor (28) ein bürstenloser Gleichstrommotor ist.
  4. Antrieb nach einem der vorhergehenden Ansprüche, worin der Antriebsmagnet (38) und der Rotormagnet (36) jeweils eine Mehrzahl Pole (42) enthalten.
  5. Antrieb nach Anspruch 4, worin der Antriebsmagnet (38) und der Rotormagnet (36) die gleiche Anzahl Pole (42) haben.
  6. Antrieb nach Anspruch 5, worin die Pole (42) des Antriebsmagneten (38) nach der Pol-Polarität mit den Polen (42) des Rotormagneten ausgerichtet sind.
  7. Antrieb nach einem der Ansprüche 4 bis 6, worin die Pole (42) des Antriebsmagneten (38) und die Pole (42) des Rotormagneten (36) in Umfangsrichtung ausgerichtet sind.
  8. Antrieb nach einem der Ansprüche 4 bis 7, worin die Antriebsplatte (34) eine Mehrzahl von radial gerichteten offenen Schlitzten (92) enthält, die eine Mehrzahl von Polen (34a) in der Antriebsplatte (34) bestimmen.
  9. Antrieb nach Anspruch 8, worin die Antriebsplatte (34) und der Antriebsmagnet (38) die gleiche Anzahl von Polen haben, welche Pole (34a) der Antriebsplatte (34) nach den Polen (42) des Antriebsmagneten (38) ausgerichtet sind.
  10. Antrieb nach Anspruch 9, worin die Antriebsplatte (34) aus kalt-gewalztem Stahl hergestellt ist.
  11. Antrieb nach Anspruch 8, worin die Antriebsplatte (34), der Antriebsmagnet (38) und der Rotormagnet (36) jeweils acht Pole haben.
  12. Antrieb nach einem der vorhergehenden Ansprüche, worin der Antriebsmagnet (38) und der Rotormagnet (36) auf eine gemeinsame Rotationsachse zentriert sind.
  13. Antrieb nach Anspruch 12, worin die gemeinsame Achse koaxial ausgerichtet ist mit der Rotationsachse der Antriebsplatte (34).
  14. Antrieb nach einem der vorhergehenden Ansprüche, zusätzlich umfassend eine zwischen den Antriebsmagneten (38) und dem Rotormagneten (36) befestigte Platte (40) aus magnetisierbarem Material.
  15. Antrieb nach Anspruch 14, worin der Rotormagnet (36), der Antriebsmagnet (38), und die Platte (40) von einer Schicht aus Kunststoff umgeben sind.
  16. Antrieb nach einem der vorhergehenden Ansprüche, zusätzlich umfassend ein erstes Gehäuse (22a) die Antriebsplatte (34) umgebend und ein zweites Gehäuse (50) den Motor (28), den Rotormagneten (36) und den Antriebsmagneten (38) umgebend, und worin die Antriebsplatte (34) rotierbar in dem ersten Gehäuse (22a) in einer eng beabstandeten, axial ausgerichteten Anordnungs-Beziehung (46) mit dem Antriebsmagneten (38) montiert ist.
  17. Antrieb nach Anspruch 16, worin in diesem engen Abstand (46)
    - (i) eine obere Wand (50a) des zweiten Gehäuses (50),
    - (ii) eine untere Wand (22b) des ersten Gehäuses (22a),
    - (iii) ein Luftspalt (56) zwischen unterer Wand (22b) und Antriebsplatte (34), und
    - (iv) ein Luftspalt (54) zwischen der oberen Wand (50a) und dem Antriebsmagneten (38) untergebracht sind.
  18. Antrieb nach Anspruch 16, worin der Antriebsmagnet (38) eine Feldstärke von ungefähr 1 400 Gauß an seiner Oberfläche hat und der enge Abstand (46), axial gemessen, ungefähr 6,35 mm (0,25 inch) beträgt.
  19. Antrieb nach einem der vorhergehenden Ansprüche, worin der Motor (28) und Antriebsmagnet (38) ein maximales Höhe-zu-Breite Verhältnis von ungefähr 1 : 3 haben, wobei die Höhe entlang der Rotationsachse des Motors (28) und des Antriebsmagneten (38) gemessen ist.
  20. Antrieb nach einem der vorhergehenden Ansprüche, worin der Motor (28) enthält eine an dem Rotor (32) befestigte und innerhalb des Stators (30) in Lagern (68) rotierbare Abgangswelle (70), eine rückwärtige Statorhalterung (64), die in ihrem Zentrum die Lager (68) trägt und die starre, im Allgemeinen zylindrisch, den Stator (30) und den Rotor (32) mit einem Spalt umgebende Seitenwände hat, und ein Deckband (76), das sich über den Spalt spannt.

21. Antrieb nach einem der vorhergehenden Ansprüche, worin der Rotormagnet (36) und Antriebsmagnet (38) jeweils ein einzelner Ringmagnet sind.
22. Antrieb nach einem der vorhergehenden Ansprüche, worin die angetriebenen Komponente (24) eine Welle (78) eines Gerätes zur Lebensmittelverarbeitung ist.
23. Antrieb nach Anspruch 22, worin das Gerät zur Lebensmittelverarbeitung ein Mixer, ein Eisapparat, ein Rührgerät, eine Universal-Küchenmaschine oder eine Fruchtpresse ist.
24. Antrieb nach Anspruch 22, worin das Gerät zur Lebensmittelverarbeitung einen Aufnahmebehälter (22) zur Aufnahme von Nahrungsmittel zu dessen Verarbeitung enthält, welcher Aufnahmebehälter ein auf der Welle (78) montiertes rotierbares Element (24) hat.
25. Antrieb nach Anspruch 24, weiter umfassend eine Dichtung (84) angeordnet um die Welle (78), um eine Flüssigkeitsdichtung zwischen dem Aufnahmebehälter (22) und der Welle (78) herzustellen.
26. Antrieb nach Anspruch 24, worin das rotierbare Element (24) eine Schneide zur Lebensmittelverarbeitung ist.
27. Antrieb nach einem der vorhergehenden Ansprüche, weiterhin umfassend eine Getriebeanordnung (306) enthaltend ein oder mehrere Getriebeübertragungsglieder (328, 332, 334) verbunden mit der Antriebsplatte (308) und der angetriebenen Komponente (14), welche Getriebeanordnung (306) das Antriebsdrehmoment von der Antriebsplatte (308) zu der angetriebenen Komponente (14) überträgt.
28. Antrieb nach Anspruch 27, worin die Getriebeanordnung (306) das von der Antriebsplatte (308) zur angetriebenen Komponente (14) übertragene Antriebsdrehmoment erhöht.
29. Antrieb nach Anspruch 27, worin die Getriebeanordnung (306) das von der Antriebsplatte (308) zur angetriebenen Komponente (14) übertragene Antriebsdrehmoment verringert.
30. Antrieb nach Anspruch 27, worin die Antriebsplatte (308) an einer Antriebswelle (326) befestigt ist, um mit der Antriebswelle (326) zu rotieren.
31. Antrieb nach Anspruch 30, worin der Antriebsmagnet (318) und der Rotormagnet (316) auf eine gemeinsame Rotationsachse zentriert sind.
32. Antrieb nach Anspruch 31, worin die gemeinsame Achse koaxial ausgerichtet ist mit der Antriebswelle (326).
33. Antrieb nach Anspruch 32, worin die angetriebenen Komponent (14) um eine von der gemeinsamen Rotationsachse versetzte Rotationsachse rotiert.
34. Antrieb nach Anspruch 30, worin ein erstes Getriebeübertragungsglied (328) der Getriebeanordnung (306) an der Antriebswelle (326) festgemacht ist, um mit dieser zu rotieren.
35. Antrieb nach Anspruch 34, worin ein zweites Getriebeübertragungsglied (334) der Getriebeanordnung (306) mit der angetriebenen Komponente (14) verbunden ist, um damit zu rotieren, das erste Getriebeübertragungsglied (328) und zweite Getriebeübertragungsglied (334) wechselwirken, um das Antriebsdrehmoment von der Antriebsplatte (308) zu der angetriebenen Komponente (14) zu übermitteln.
36. Antrieb nach Anspruch 35, worin die Getriebeanordnung (306) darüberhinaus ein drittes Getriebeübertragungsglied (332) umfasst, das zwischen dem ersten Getriebeübertragungsglied (328) und dem zweiten Getriebeübertragungsglied (334) positioniert ist, und welches dritte Getriebeübertragungsglied (332) mit dem ersten Getriebeübertragungsglied (328) und dem zweiten Getriebeübertragungsglied (334) wechselwirkt um das Antriebsdrehmoment zwischen diesen zu übertragen.
37. Antrieb nach einem der vorhergehenden Ansprüche, weiterhin umfassend eine Steuer- und Antriebseinheit elektrisch verbunden mit dem Motor (28), um den Betrieb des Motors (28) zu steuern, welche Steuer- und Antriebseinheit selektiv den Stator (30) unter Strom setzt, um ein Arbeitsdrehmoment oder ein Bremsdrehmoment auf den Rotor (32) zu erzeugen.
38. Antrieb nach Anspruch 37, worin der Stator (30) eine oder mehrere Statorwicklungen enthält.
39. Antrieb nach Anspruch 38, worin die Steuer- und Antriebseinheit den Strom durch die Statorwicklungen verändert, um das Arbeitsdrehmoment oder das Bremsdrehmoment zu erzeugen.
40. Antrieb nach Anspruch 37, weiterhin einen oder mehrere mit der Steuer- und Antriebseinheit verbundene Positionssensoren umfassend, um die Position des Rotors (32) zu überwachen.
41. Antrieb nach Anspruch 40, worin die Positionssensoren Hallsensoren sind.

42. Verfahren zum Betrieb eines Gerätes zur Lebensmittelverarbeitung, welches Gerät zur Lebensmittelverarbeitung enthält,

in einen Aufnahmebehälter (22), der ein auf einer Welle (78) montiertes rotierbares Element (24) hat,

eine Antriebsplatte (34), hergestellt aus magnetisierbarem Material, befestigt an der Welle (78), um damit zu rotieren,

und eine Magnetanordnung (36, 38), magnetisch gekoppelt mit einem Motor (28) und der Antriebsplatte (34), welches Verfahren umfasst die Schritte:

Übertragen eines Arbeitsdrehmomentes bei einer Arbeitsgeschwindigkeit von dem Motor (28) zu der Antriebsplatte (34) durch die Magnetanordnung (36, 38), um eine Rotation der Welle (78) und des rotierbaren Element (24) herbeizuführen, und

Übertragen eines Bremsdrehmomentes von dem Motor (28) zu der Antriebsplatte (34) durch die Magnetanordnung (36, 38), um die Rotation der Welle (78) und des rotierbaren Element (24) zu beenden.

43. Verfahren nach Anspruch 42, worin das Arbeitsdrehmoment und das Bremsdrehmoment von dem Motor (28) zu der Antriebsplatte (34) übertragen werden, ohne mechanische Verbindung der Antriebsplatte (34) zu dem Motor (28).

44. Verfahren nach Anspruch 42, worin der Schritt des Übertragens eines Arbeitsdrehmomentes umfasst Übertragen eines Anfahr-drehmomentes vom Motor (28) zur Antriebsplatte (34), Steigern der Rotationsgeschwindigkeit der Antriebsplatte (34) bis zur Arbeitsgeschwindigkeit, und Aufrechterhalten der Arbeitsgeschwindigkeit bei dem Arbeitsdrehmoment.

45. Verfahren nach Anspruch 42, worin der Motor (28) ein bürstenloser Gleichstrommotor ist, der ein oder mehrere Statorwicklungen (30) hat und worin das Arbeitsdrehmoment und das Bremsdrehmoment durch Verändern des Stroms durch die Statorwicklungen (30) erzeugt werden.

46. Gerät zur Lebensmittelverarbeitung umfassend:

ein Mixgerät umfassend

einen Mixgerätbecher (22), der eine erste rotierend auf einer ersten Welle (78) befestigte Schneide (24) hat,

eine erste Antriebsplatte (34), hergestellt aus magnetisierbarem Material, befestigt an der ersten Welle (78), um damit zu rotieren,

einen ersten Motor (28) positioniert nahe der ersten Antriebsplatte (34), welcher erster Motor (28) einen ersten Stat r (30) und einen ersten

Rotor (32) hat, welcher erster Rotor (30) einen ersten Rotormagneten (36) enthält, welcher erster Stator (30) ein elektromagnetisches Feld erzeugt, das mit dem ersten Rotormagneten (36) wechselwirkt, um den ersten Rotormagneten (36) in Rotation zu versetzen,

einen ersten Antriebsmagnet (38), verbunden mit dem ersten Rotormagneten (36), um damit zu rotieren, welcher erster Antriebsmagnet (38) ein magnetisches Feld in Richtung der ersten Antriebsplatte (34) induziert, um ein Antriebsdrehmoment von dem ersten Motor (28) zu der ersten Antriebsplatte (34) zu übermitteln, dabei die erste Welle (78) und die erste Schneide (24) drehend; und

einen Eisapparat zur Versorgung des Mixgerätes mit geschnittenem Eis, der Eisapparat umfassend

einen Eiseinfülltrichter (12), der eine zweite Schneide (14) hat, die rotierend auf einer zweiten Welle (302) angebracht ist, und welcher Eiseinfülltrichter (12) einen mit dem Mixgerät (22) zur Versorgung des Mixgerätes (22) mit geschnittenem Eis verbundenen Einzugschacht (16) enthält,

eine zweite Antriebsplatte (308), hergestellt aus magnetisierbarem Material,

einen zweiten Motor (310), nahe der zweiten Antriebsplatte (308) positioniert, welcher zweiter Motor (310) einen zweiten Stator (312) und einen zweiten Rotor (314) hat, welcher zweiter Rotor (314) einen zweiten Rotormagneten (316) enthält, welcher zweiter Stator (312) ein elektromagnetisches Feld erzeugt, das mit dem zweiten Rotormagneten (314), wechselwirkt um den zweiten Rotormagneten (316) in Rotation zu setzen,

einen zweiten Antriebsmagnet (318), verbunden mit dem zweiten Rotormagneten (316), um damit zu rotieren, welcher zweiter Antriebsmagnet (318) ein magnetisches Feld in Richtung der zweiten Antriebsplatte (308) induziert, um das Drehmoment von dem zweiten Motor (310) zu der zweiten Antriebsplatte (308) zu übertragen, und

eine Getriebeanordnung (306), die ein oder mehrere mit der zweiten Antriebsplatte (308) und der zweiten Welle (302) verbundene Getriebeübertragungsglieder (328, 332, 334) enthält, welche Getriebeanordnung (306) das Antriebsdrehmoment von der zweiten Antriebsplatte (308) zur zweiten Welle (302) überträgt, um dadurch das Schneiden von Eis mit der zweiten Schneide (14) zu bewirken.



## Revendications

1. Mécanisme d'entraînement (26) pour faire tourner un élément entraîné (24), ledit mécanisme d'entraînement comprenant :

- un plateau d'entraînement (34) formé d'un matériau magnétisable couplé audit élément entraîné (24) pour tourner avec lui,
- un moteur (28) positionné à proximité dudit plateau d'entraînement (34), ledit moteur ayant un stator (30) et un rotor (32), ledit rotor (32) incluant un aimant de rotor (36), ledit stator (30) produisant un champ électromagnétique qui interagit avec ledit aimant de rotor (36) pour faire tourner ledit aimant de rotor (36), et
- un aimant d'entraînement (38) couplé audit aimant de rotor (36) pour tourner avec lui, ledit aimant d'entraînement (38) induisant un champ magnétique dans une direction orientée vers ledit plateau d'entraînement (34) pour transmettre un couple d'entraînement audit plateau d'entraînement (34) à partir dudit moteur (28) afin de faire tourner ledit élément entraîné (24).

2. Mécanisme d'entraînement selon la revendication 1, dans lequel ledit moteur (28) est un moteur électrique.

3. Mécanisme d'entraînement selon la revendication 2, dans lequel ledit moteur électrique (28) est un moteur à courant continu sans balai.

4. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, dans lequel ledit aimant d'entraînement (38) et ledit aimant de rotor (36) incluent chacun une pluralité de pôles (42).

5. Mécanisme d'entraînement selon la revendication 4, dans lequel ledit aimant d'entraînement (38) et ledit aimant de rotor (36) ont un nombre analogue de pôles (42).

6. Mécanisme d'entraînement selon la revendication 5, dans lequel lesdits pôles (42) dudit aimant d'entraînement (38) sont alignés par polarité polaire avec lesdits pôles (42) dudit aimant de rotor (36).

7. Mécanisme d'entraînement selon l'une quelconque des revendications 4 à 6, dans lequel lesdits pôles (42) dudit aimant d'entraînement (38) et lesdits pôles (42) dudit aimant de rotor (36) sont alignés de façon circonferentielle.

8. Mécanisme d'entraînement selon l'une quelconque des revendications 4 à 7, dans lequel ledit plateau d'entraînement (34) inclut une pluralité de fentes ouvertes (92) dirigées radialement qui définissent

un pluralité de pôles (34a) sur ledit plateau d'entraînement (34).

9. Mécanisme d'entraînement selon la revendication 8, dans lequel ledit plateau d'entraînement (34) et ledit aimant d'entraînement (38) ont un nombre analogue de pôles, lesdits pôles (34a) dudit plateau d'entraînement (34) étant alignés avec lesdits pôles (42) dudit aimant d'entraînement (38).

10. Mécanisme d'entraînement selon la revendication 9, dans lequel ledit plateau d'entraînement (34) est formé d'acier laminé à froid.

11. Mécanisme d'entraînement selon la revendication 8, dans lequel ledit plateau d'entraînement (34), ledit aimant d'entraînement (38) et ledit aimant de rotor (36) ont chacun huit pôles.

12. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, dans lequel ledit aimant d'entraînement (38) et ledit aimant de rotor (36) sont centrés sur un axe commun de rotation.

13. Mécanisme d'entraînement selon la revendication 12, dans lequel ledit axe commun est coaxialement aligné avec l'axe de rotation dudit plateau d'entraînement (34).

14. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, comprenant de plus un plateau (40) de matériau magnétisable fixé entre ledit aimant d'entraînement (38) et ledit aimant de rotor (36).

15. Mécanisme d'entraînement selon la revendication 14, dans lequel ledit aimant de rotor (36), ledit aimant d'entraînement (38) et ledit plateau (40) sont enfermés dans une couche d'une matière plastique (48).

16. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, comprenant de plus un premier boîtier (22a) enfermant ledit plateau d'entraînement (34) et un deuxième boîtier (50) enfermant ledit moteur (28), ledit aimant de rotor (36), et ledit aimant d'entraînement (38), et dans lequel ledit plateau d'entraînement (34) est monté rotatif dans ledit premier boîtier (22a) en relation alignée axialement, étroitement espacée (46) avec ledit aimant d'entraînement (38).

17. Mécanisme d'entraînement selon la revendication 16, dans lequel ledit espacement étroit (46) contient (i) une paroi supérieure (50a) dudit deuxième boîtier (50), (ii) une paroi inférieure (22b) dudit premier boîtier (22a), (iii) un intervalle d'air (56) entre ledit paroi inférieure (22b) et ledit plateau d'entraînement (34).

ment (34), et (iv) un intervalle d'air (54) entre ladite paroi supérieure (50a) et ledit aimant d'entraînement (38).

18. Mécanisme d'entraînement selon la revendication 16, dans lequel ledit aimant d'entraînement (38) possède une intensité de champ d'environ 1 400 gauss à sa surface et ledit espacement étroit (46), mesuré axialement, est d'environ 6,35 mm (0,25 inch).

19. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, dans lequel lesdits moteur (28) et aimant d'entraînement (38) ont un rapport hauteur-à-largeur maximum d'environ 1/3, où la hauteur est mesurée le long de l'axe de rotation dudit moteur (28) et dudit aimant d'entraînement (38).

20. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, dans lequel ledit moteur (28) inclut un arbre de sortie (70) fixé audit rotor (32) et pouvant tourner à l'intérieur dudit stator (30) dans des paliers (68), un support arrière (64) de stator qui supporte lesdits paliers (68) en son centre et possède des parois latérales généralement cylindriques, rigides, entourant ledit stator (30) et ledit rotor (32) avec un intervalle, et un carénage (76) qui englobe ledit intervalle.

21. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, dans lequel lesdits aimant de rotor (36) et aimant d'entraînement (38) sont chacun un aimant annulaire unique.

22. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, dans lequel ledit élément entraîné (24) est un arbre (78) d'un appareil de traitement de nourriture.

23. Mécanisme d'entraînement selon la revendication 22, dans lequel ledit appareil de traitement de nourriture est un mélangeur, un broyeur de glace, un mélangeur d'aliments, un robot de cuisine ou un presse-fruit.

24. Mécanisme d'entraînement selon la revendication 22, dans lequel ledit appareil de traitement de nourriture inclut un réceptacle (22) pour recevoir les aliments à traiter, ledit réceptacle ayant un élément rotatif (24) monté sur ledit arbre (78).

25. Mécanisme d'entraînement selon la revendication 24, comprenant de plus un joint d'étanchéité (84) positionné autour dudit arbre (78) pour fournir un joint d'étanchéité aux fluides entre ledit réceptacle (22) et ledit arbre (78).

26. Mécanisme d'entraînement selon la revendication 24, dans lequel ledit élément rotatif (24) est un couteau pour traiter les aliments.

27. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, comprenant de plus une pignonnerie (306) incluant une ou plusieurs roues d'engrenage (328, 332, 334) couplées audit plateau d'entraînement (308) et audit élément entraîné (14), ladite pignonnerie (306) transmettant ledit couple d'entraînement dudit plateau d'entraînement (308) audit élément entraîné (14).

28. Mécanisme d'entraînement selon la revendication 27, dans lequel la pignonnerie (306) augmente le couple d'entraînement transmis dudit plateau d'entraînement (308) audit élément entraîné (14).

29. Mécanisme d'entraînement selon la revendication 27, dans lequel la pignonnerie (306) diminue le couple d'entraînement transmis dudit plateau d'entraînement (308) audit élément entraîné (14).

30. Mécanisme d'entraînement selon la revendication 27, dans lequel ledit plateau d'entraînement (308) est fixé à un arbre d'entraînement (326) pour tourner avec ledit arbre d'entraînement (326).

31. Mécanisme d'entraînement selon la revendication 30, dans lequel ledit aimant d'entraînement (318) et ledit aimant de rotor (316) sont centrés sur un axe commun de rotation.

32. Mécanisme d'entraînement selon la revendication 31, dans lequel ledit axe commun est aligné coaxialement avec ledit arbre d'entraînement (326).

33. Mécanisme d'entraînement selon la revendication 32, dans lequel ledit élément entraîné (14) tourne autour d'un axe de rotation décalé dudit axe commun de rotation.

34. Mécanisme d'entraînement selon la revendication 30, dans lequel une première roue d'engrenage (328) de ladite pignonnerie (306) est fixée audit arbre d'entraînement (326) pour tourner avec lui.

35. Mécanisme d'entraînement selon la revendication 34, dans lequel une deuxième roue d'engrenage (334) de ladite pignonnerie (306) est couplée audit élément entraîné (14) pour tourner avec lui, lesdites première roue d'engrenage (328) et deuxième roue d'engrenage (334) interagissant pour transmettre ledit couple d'entraînement dudit plateau d'entraînement (308) audit élément entraîné (14).

36. Mécanisme d'entraînement selon la revendication 35, dans lequel ladite pignonnerie (306) comprend

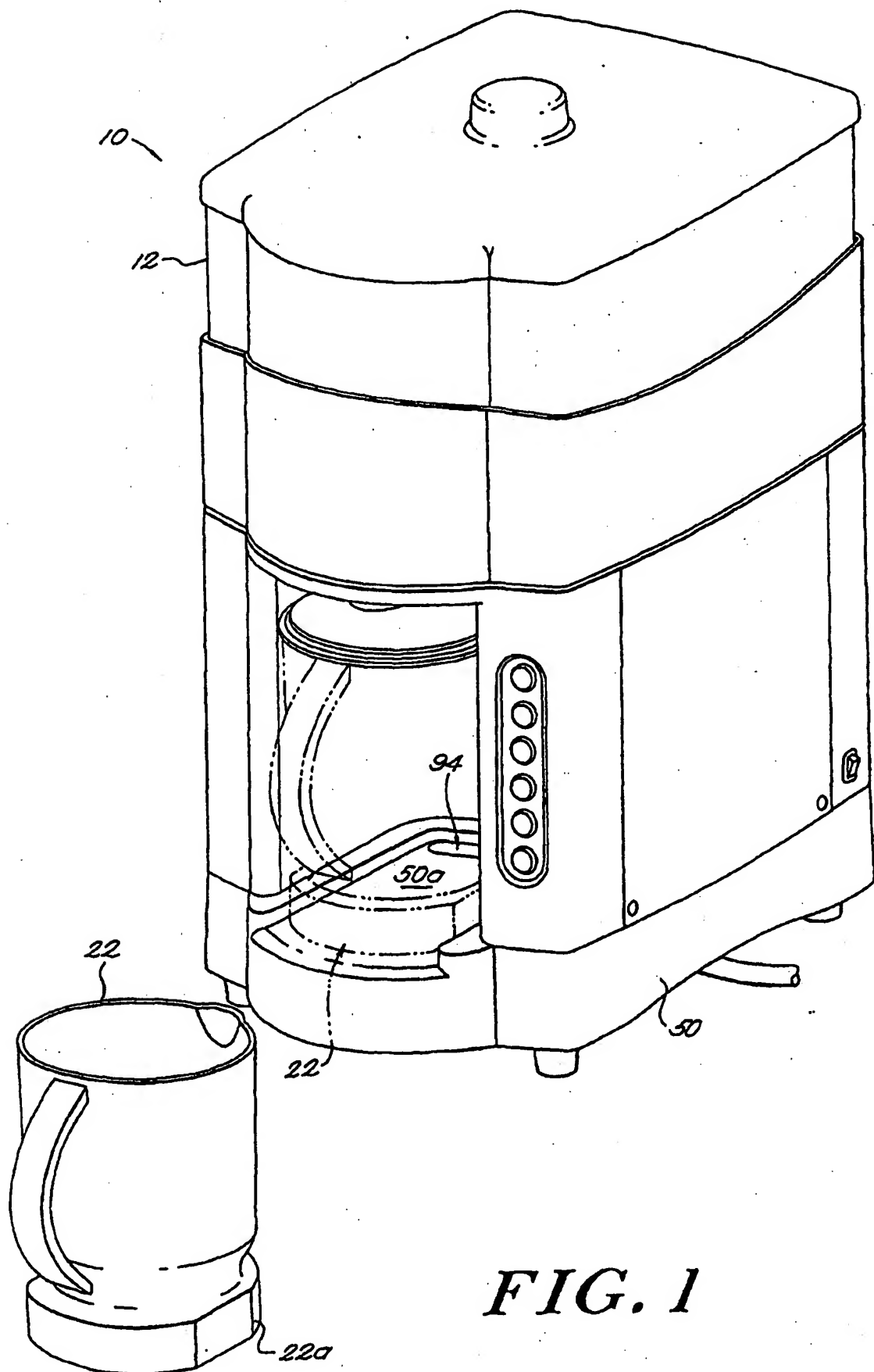
- de plus une troisième roue d'engrenage (332) interposée entre ladite première roue d'engrenage (328) ladite deuxième roue d'engrenage (334), ladite troisième roue d'engrenage (332) interagissant avec ladite première roue d'engrenage (328) et ladite deuxième roue d'engrenage (334) pour transmettre ledit couple d'entraînement entre elles.
37. Mécanisme d'entraînement selon l'une quelconque des revendications précédentes, comprenant de plus une unité de commande et d'entraînement électriquement couplée audit moteur (28) pour commander le fonctionnement dudit moteur (28), ladite unité de commande et d'entraînement mettant sélectivement sous tension ledit stator (30) pour produire un couple moteur ou un couple de freinage sur ledit rotor (32).
38. Mécanisme d'entraînement selon la revendication 37, dans lequel ledit stator (30) inclut une ou plusieurs bobines de stator.
39. Mécanisme d'entraînement selon la revendication 38, dans lequel ladite unité de commande et d'entraînement fait varier le courant à travers les bobines de stator pour produire ledit couple moteur ou ledit couple de freinage.
40. Mécanisme d'entraînement selon la revendication 37, comprenant de plus un ou plusieurs détecteurs de position couplés à ladite unité de commande et d'entraînement pour contrôler la position dudit rotor (32).
41. Mécanisme d'entraînement selon la revendication 40, dans lequel les détecteurs de position sont des détecteurs à effet Hall.
42. Procédé pour faire fonctionner un appareil de traitement de nourriture, l'appareil de traitement de nourriture incluant un réceptacle de nourriture (22) ayant un élément rotatif (24) monté sur un arbre (78), un plateau d'entraînement (34) formé de matériau magnétisable fixé audit arbre (78) pour tourner avec lui, et un assemblage d'aimants (36, 38) couplé magnétiquement à un moteur (28) et audit plateau d'entraînement (34), le procédé comprenant les étapes consistant à :
- transmettre un couple moteur à une vitesse de fonctionnement audit plateau d'entraînement (34) à partir dudit moteur (28) par l'intermédiaire dudit assemblage d'aimants (36, 38) pour effectuer une rotation dudit arbre (78) et dudit élément rotatif (24), et
  - transmettre un couple de freinage audit plateau d'entraînement (34) à partir dudit moteur (28) par l'intermédiaire dudit assemblage d'aimants
- (36, 38) pour terminer la rotation dudit arbre (78) et dudit élément rotatif (24).
43. Procédé selon la revendication 42, dans lequel ledit couple moteur et ledit couple de freinage sont transmis audit plateau d'entraînement (34) à partir dudit moteur (28) sans couplage mécanique dudit plateau d'entraînement (34) audit moteur (28).
44. Procédé selon la revendication 42, dans lequel l'étape consistant à transmettre un couple moteur comprend les étapes consistant à :
- transmettre un couple de démarrage dudit moteur (28) vers ledit plateau d'entraînement (34),
  - augmenter la vitesse de rotation dudit plateau d'entraînement (34) jusqu'à ladite vitesse de fonctionnement, et
  - maintenir ladite vitesse de fonctionnement audit couple moteur.
45. Procédé selon la revendication 42, dans lequel le moteur (28) est un moteur à courant continu sans balai ayant une ou plusieurs bobines de stator (30) et dans lequel ledit couple moteur et ledit couple de freinage sont engendrés en faisant varier le courant à travers lesdites bobines de stator (30).
46. Appareil de traitement de nourriture comprenant :
- un mélangeur comprenant
    - un bol de mélangeur (22) ayant un premier couteau (24) monté rotatif sur un premier arbre (78),
    - un premier plateau d'entraînement (34) formé d'un matériau magnétisable fixé audit premier arbre (78) pour tourner avec lui,
    - un premier moteur (28) positionné à proximité dudit premier plateau d'entraînement (34), ledit premier moteur (28) ayant un premier stator (30) et un premier rotor (32), ledit premier rotor (30) incluant un premier aimant de rotor (36), ledit premier stator (30) produisant un champ électromagnétique qui interagit avec ledit premier aimant de rotor (36) pour faire tourner ledit premier aimant de rotor (36),
    - un premier aimant d'entraînement (38) couplé audit premier aimant de rotor (36) pour tourner avec lui, ledit premier aimant d'entraînement (38) induisant un champ magnétique dans une direction orientée vers ledit premier plateau d'entraînement (34) pour transmettre un couple d'entraînement audit premier plateau d'entraînement (34) à partir dudit premier moteur (28), faisant ainsi tourner ledit premier arbre (78)

et ledit premier couteau (24) ; et

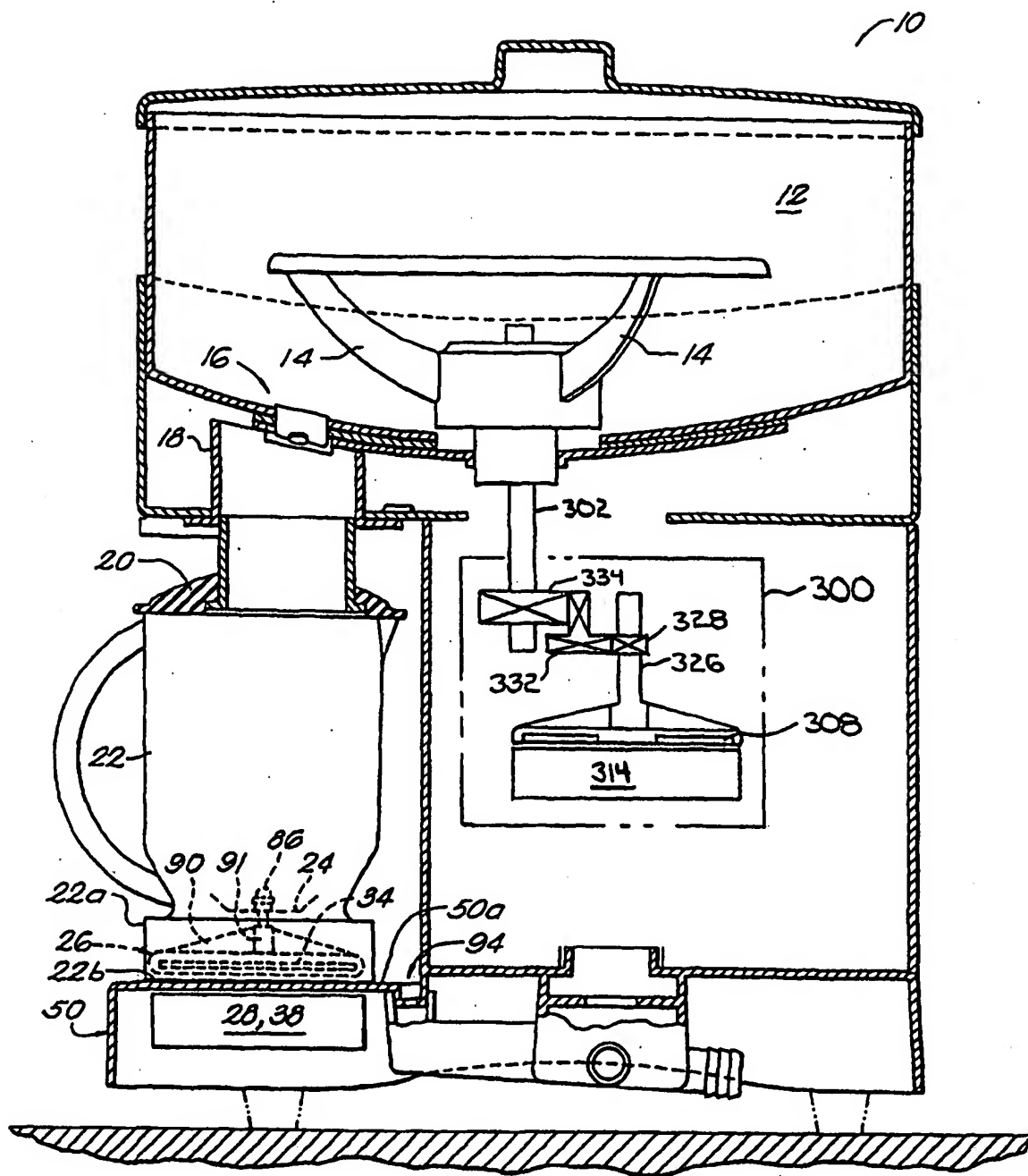
- un broyeur de glace pour fournir de la glace pilée audit mélangeur, ledit broyeur de glace comprenant 5
- une trémie de glace (12) ayant un deuxième couteau (14) monté rotatif sur un deuxième arbre (302), et ladite trémie de glace (12) incluant une goulotte (16) reliée 10 audit bol de mélangeur (22) pour fournir de la glace pilée audit bol de mélangeur (22),
- un deuxième plateau d'entraînement (308) formé de matériau magnétisable,
- un deuxième moteur (310) positionné à 15 proximité dudit deuxième plateau d'entraînement (308), ledit deuxième moteur (310) ayant un deuxième stator (312) et un deuxième rotor (314), ledit deuxième rotor (314) incluant un deuxième aimant de rotor 20 (316), ledit deuxième stator (312) produisant un champ électromagnétique qui interagit avec ledit deuxième aimant de rotor (314) pour faire tourner ledit deuxième aimant de rotor (316), 25
- un deuxième aimant d'entraînement (318) couplé audit deuxième aimant de rotor (316) pour tourner avec lui, ledit deuxième aimant d'entraînement (318) induisant un champ magnétique dans une direction 30 orientée vers ledit deuxième plateau d'entraînement (308) pour transmettre un couple audit deuxième plateau d'entraînement (308) à partir dudit deuxième moteur (310), et 35
- une pignonnerie (306) incluant une ou plusieurs roues d'engrenage (328,332,334) couplée audit deuxième plateau d'entraînement (308) et audit deuxième arbre (302), ladite pignonnerie (306) transmettant ledit couple d'entraînement dudit 40 deuxième plateau d'entraînement (308) audit deuxième arbre (302) pour réaliser le broyage de ladite glace avec ledit deuxième couteau (14). 45

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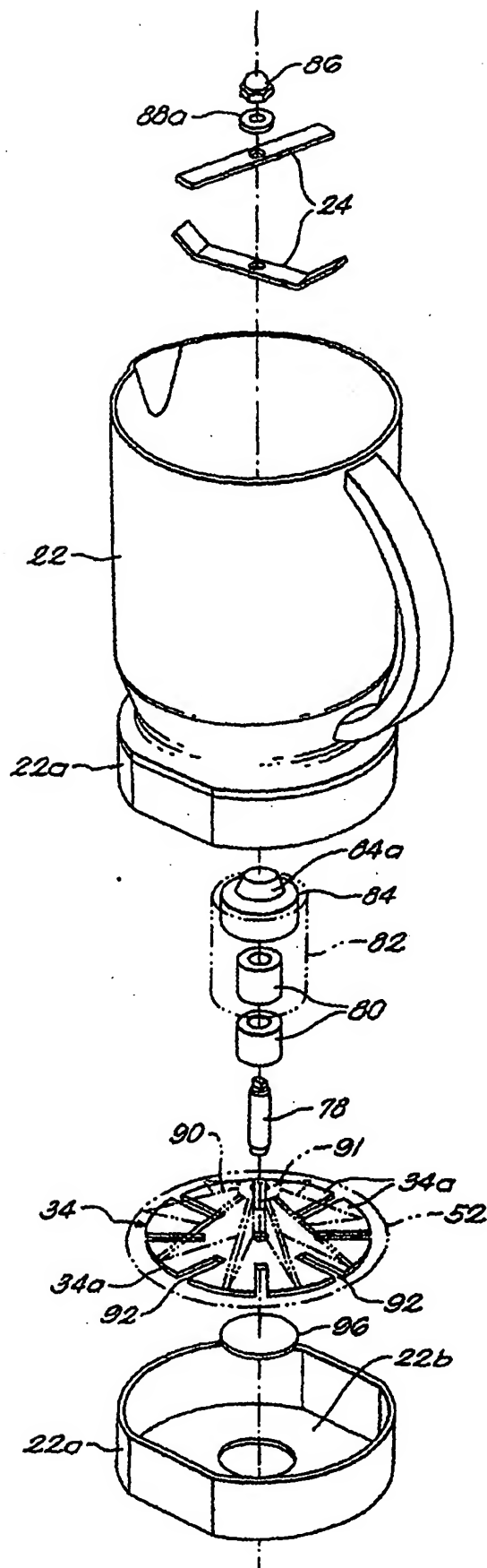


**FIG. 1**



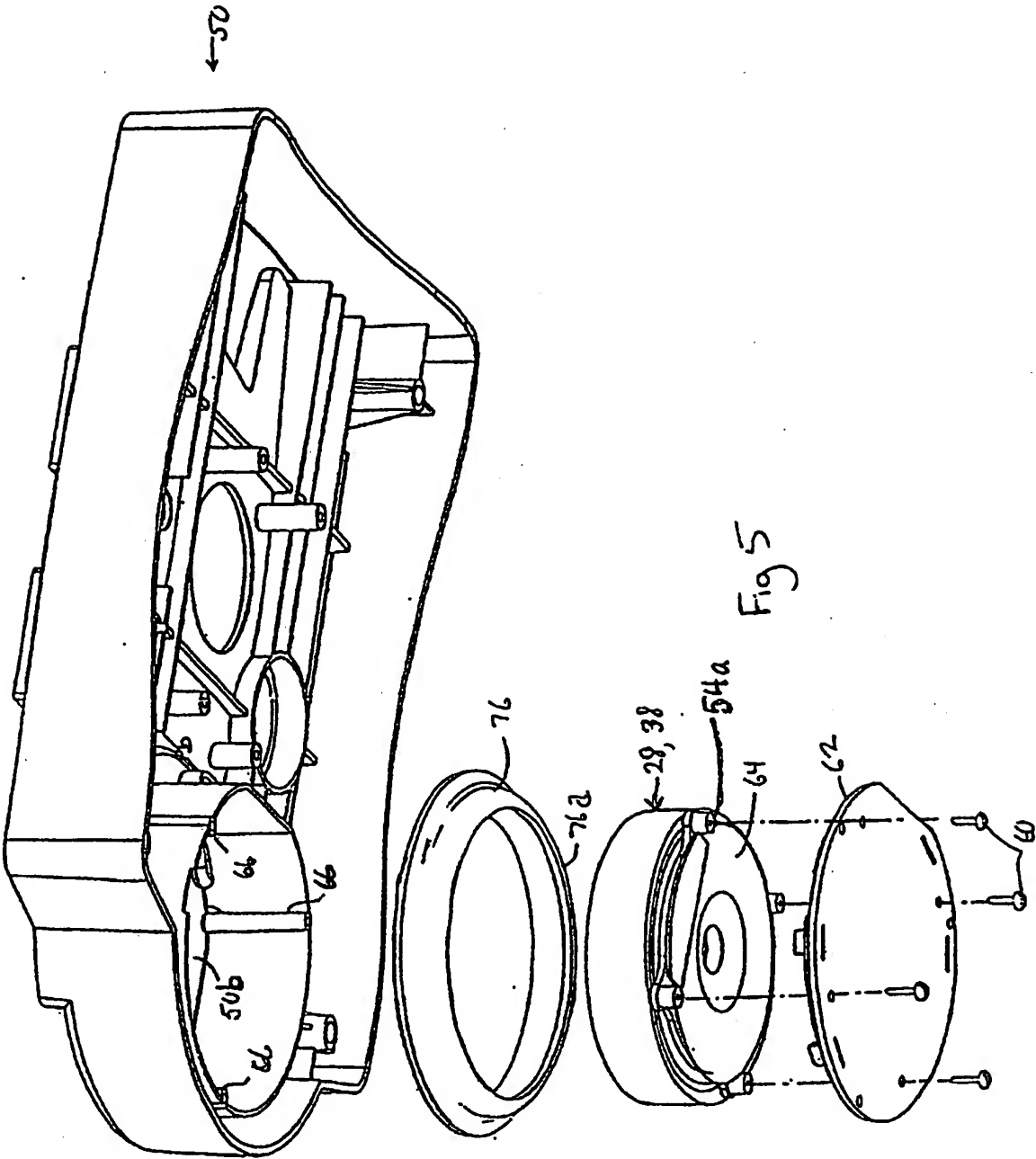
**FIG. 2**

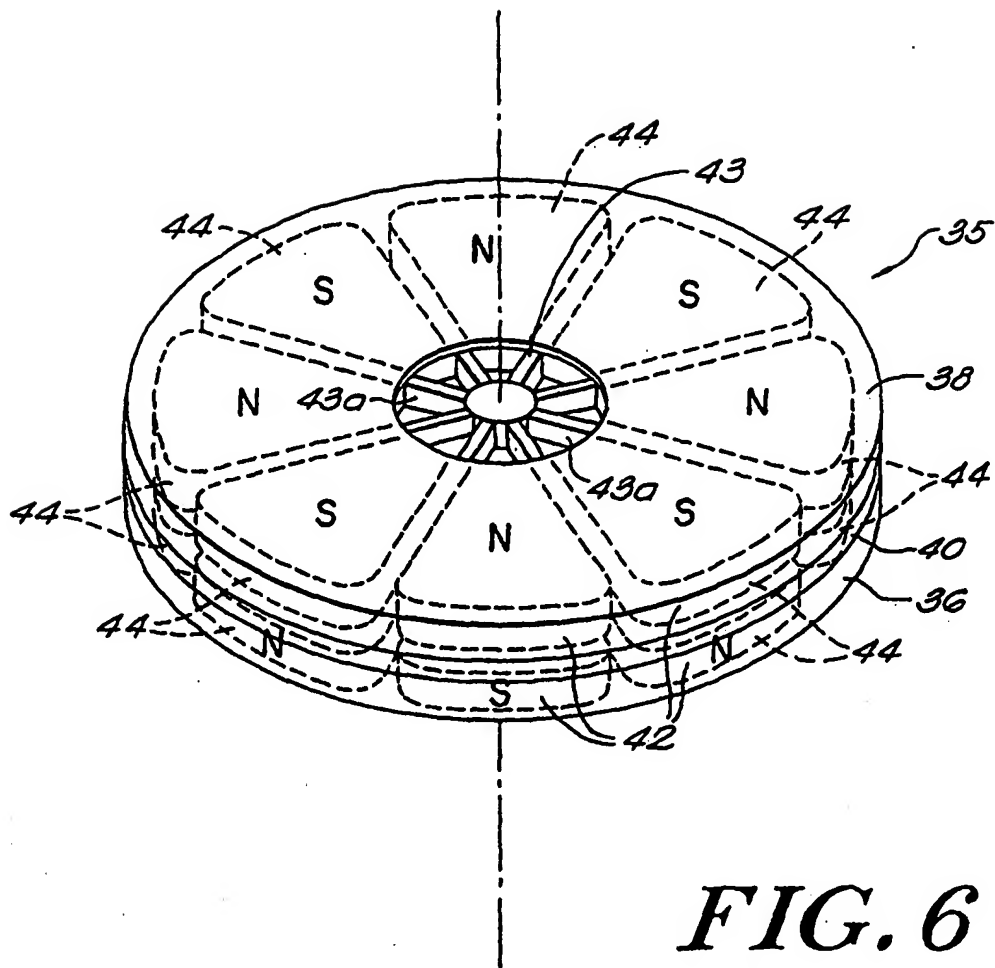




**FIG. 3**







**FIG. 6**

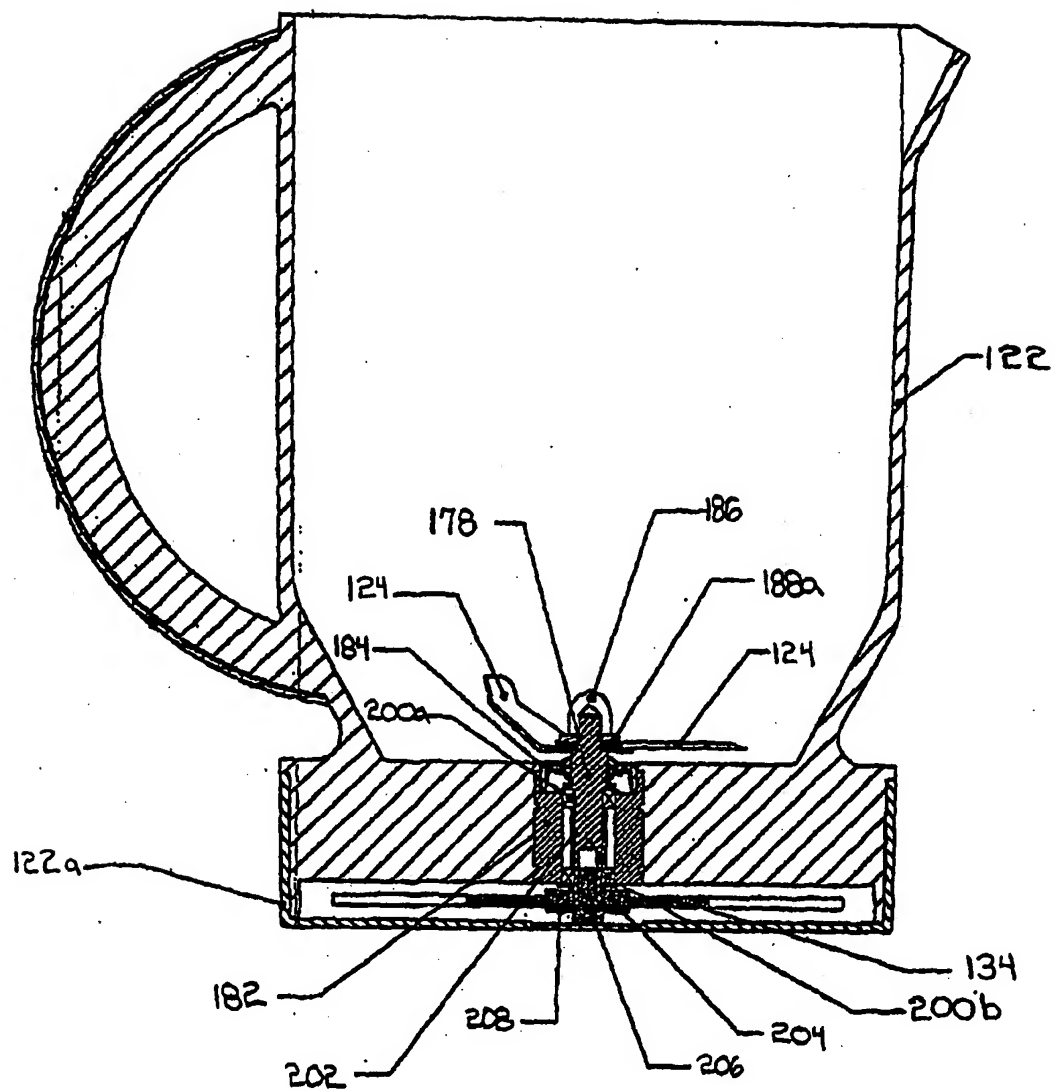


FIG. 7

Fig. 8

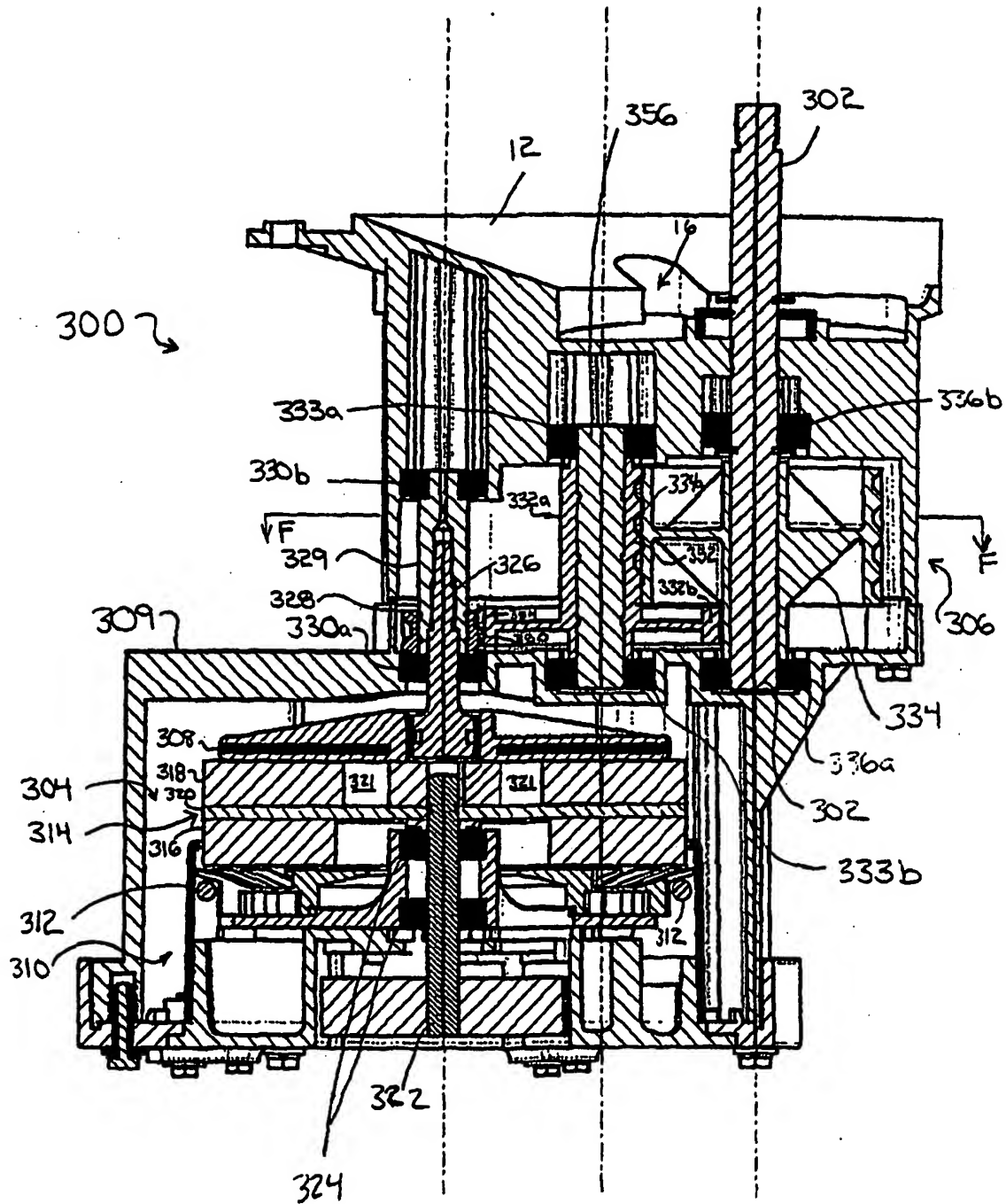




FIG. 9

